

New exp ($Q(\xi)$)-Expansion Method for Solving New Model of Extension System Nonlinear Partial Differential Equations

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Abstract

In this paper, we presented new method, namely, the exp ($Q(\xi)$)-expansion method is proposed for constructing more general and a rich class of new exact traveling wave solutions of nonlinear partial differential equations (NLPDEs). This method has been applied to new the extension system Boussinesq equations (esB). Exact travelling wave solutions are obtained and expressed in terms of hyperbolic functions, trigonometric functions and rational functions.

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Key Words: exp ($Q(\xi)$)- expansion method, extension system Boussinesq equations (esB), traveling wave solutions.

1 Introduction

In recent years, a wide range of straightforward and effective methods have been introduced to obtain traveling wave solutions of nonlinear (PDEs). Such methods, the sine-cosine method [1, 2], the tanh-coth method [3, 4], the multiple-soliton solutions [5]-[7], the $(\frac{1}{G'})$ -expansion method [8], the mapping method [9], the improved F-expansion scheme [10], the Adomain decomposition approach [11, 12], the modified trial equation method [13], Darboux transformation [14], the $(\frac{G'}{G})$ -expansion method [15, 16], the improved and generalized $(\frac{G'}{G})$ expansion methods [17], the $(\frac{G'}{G^2})$ -expansion

method [18, 19], the extended hyperbolic function method [20], the Residual power series method [21], the Jacobi elliptic function expansion method [22], the $\left(\frac{G'}{G}, \frac{1}{G}\right)$ -expansion method [23]-[25], the improved tan $(\varphi(\xi)/2)$ -expansion method [26]. Sometimes, numerical techniques are good alternatives to analytical ones, for instance, see [27, 28].

The importance of our present work is, in order to generate many exact traveling wave solutions, new approach $\exp(Q(\xi))$ -expansion method. For illustration and to depict of the proposed method, new the extension system Boussinesq equations (*esB*) has been studied and generated abundant and more types of new travelling wave solutions.

2 Description of new method

Consider the general nonlinear partial differential equations (PDEs), say, in two variables,

$$\Psi(v, v_t, v_x, v_{tt}, v_{xt}, v_{xx}, \dots) = 0, \quad (1)$$

where $v = v(x, t)$ is an unknown function, Ψ is a polynomial in $v(x, t)$ and the subscripts stand for the partial derivatives.

We suppose that the combination of real variables x and t by a complex variable ξ

$$v(x, t) = v(\xi), \quad \xi = ax - ct, \quad (2)$$

where a is the wave number and c is the speed of the traveling wave. Now using Eq. (2), Eq. (1) is converted into an ordinary differential equation for $v = v(\xi)$:

$$\Phi(v, -cv', av', c^2v'', -cav'', a^2v'', \dots) = 0, \quad \prime \equiv \frac{d}{d\xi}. \quad (3)$$

Suppose the traveling wave solution of Eq. (3) can be expressed by polynomial in $\exp(Q(\xi))$ as:

$$v(\xi) = \sum_{i=0}^N a_i (\exp(Q(\xi)))^i, \quad (4)$$

where the coefficients a_i ($0 \leq i \leq N$), a and c are constants to be determined, such that $a_N \neq 0$ and $Q = Q(\xi)$ satisfies the following ordinary differential equation:

$$Q'(\xi) = \sqrt{\mu \exp(Q(\xi)) + \lambda}, \quad (5)$$

Eq. (5) gives the following solutions:

Case 1. where $\lambda > 0$ and $\mu \neq 0$,

$$Q(\xi) = \ln \left(\frac{-\lambda}{\mu} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} (\xi + k) \right) \right), \quad (6)$$

$$Q(\xi) = \ln \left(\frac{\lambda}{\mu} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} (\xi + k) \right) \right), \quad (7)$$

where k is a constant of integration.

Case 2. where $\lambda < 0$ and $\mu \neq 0$,

$$Q(\xi) = \ln \left(\frac{-\lambda}{\mu} \sec^2 \left(\frac{\sqrt{-\lambda}}{2} (\xi + k) \right) \right), \quad (8)$$

$$Q(\xi) = \ln \left(\frac{-\lambda}{\mu} \csc^2 \left(\frac{\sqrt{-\lambda}}{2} (\xi + k) \right) \right). \quad (9)$$

Case 3. where $\lambda = 0$ and $\mu \neq 0$,

$$Q(\xi) = \ln \left(\frac{4}{\mu(\xi + k)^2} \right). \quad (10)$$

Case 4. where $\lambda = \theta^2$ and $\mu \neq 0$,

$$Q(\xi) = \ln \left(\frac{\theta^2}{\mu} \left(\left(\frac{1 + \exp(\theta(\xi + k))}{1 - \exp(\theta(\xi + k))} \right)^2 - 1 \right) \right). \quad (11)$$

Case 5. where $\lambda \neq 0$ and $\mu = 0$,

$$Q(\xi) = \sqrt{\lambda}(\xi + k). \quad (12)$$

Where $\theta, a_i (i = 0, 1, 2, \dots, N), a, c, \mu$ and λ are constants. The positive integer N can be determined by using homogeneous balance between the highest order derivatives and the nonlinear terms appearing in ODE (3). Substituting Eq. (4) into Eq. (3), using Eq. (5) repeatedly, and setting the coefficients of the each order of $(\exp(Q(\xi)))^i, (\exp(Q(\xi)))^i \sqrt{\mu \exp(Q(\xi)) + \lambda}$ to zero, we obtain a set of nonlinear algebraic equations for $a_i (i = 0, 1, 2, \dots, N)$, a, c, μ and λ . With the aid of the computer program Maple, we can solve the set of nonlinear algebraic equations and obtain all the constants $a_i (i = 0, 1, 2, \dots, N)$.

$0, 1, 2, \dots, N), a, c$. Substituting the values of $a_i (i = 0, 1, 2, \dots, N), a, c$ into Eq. (4) along with general solutions of Eq. (5) completes the determination of the solution of Eq. (1).

3 The esB equation

Consider the extension system Boussinesq equations (esB) that reads:

$$\begin{cases} v_t + A(u^2)_x - Eu_{xxx} = 0 \\ u_t - Pv_x - Lw_x = 0 \\ w_t - Bu_x = 0. \end{cases} \quad (13)$$

Where A, B, E, P and L are constants.

Applying the following wave transformation

$$u(x, t) = u(\xi), v(x, t) = v(\xi) \text{ and } w(x, t) = w(\xi), \text{ where } \xi = ax - ct. \quad (14)$$

On equation Eq. (13), we get

$$\begin{cases} -cv' + aA(u^2)' - a^3Eu''' = 0 \\ -cu' - aPv' - aLw' = 0 \\ -cw' - aBu' = 0. \end{cases} \quad (15)$$

Integrating Eq. (15) once with respect to ξ , yields

$$\begin{cases} -cv + aAu^2 - a^3Eu'' = 0 \\ -cu - aPv - aLw = 0 \\ -cw - aBu = 0. \end{cases} \quad (16)$$

For finding the value N , we use balancing principle on Eq. (16), and get $N = 2$.

From Eq. (4), we have

$$\begin{aligned} u(\xi) &= a_0 + a_1 \exp(Q(\xi)) + a_2 (\exp(Q(\xi)))^2, \\ v(\xi) &= b_0 + b_1 \exp(Q(\xi)) \\ &\quad + b_2 (\exp(Q(\xi)))^2, \\ w(\xi) &= d_0 + d_1 \exp(Q(\xi)) + d_2 (\exp(Q(\xi)))^2, \end{aligned} \quad (17)$$

where $a_0, a_1, a_2, b_0, b_1, b_2, d_0, d_1$ and d_2 are arbitrary constants.

Substituting Eq. (17) in Eq. (16) and using Eq. (5), collecting the coefficients of each power of $(\exp(Q(\xi)))^i$, $0 \leq i \leq 4$, setting each coefficients to zero, and solving the algebraic equations by Maple we get,

set (1).

$$\begin{aligned} a_0 &= 0, a_1 = \frac{3Ea^2\mu}{2A}, a_2 = 0, b_0 = 0, b_1 = \frac{\mp 3E^2a^4\lambda\mu}{2A\sqrt{Ea^2\lambda P + BL}}, b_2 = 0, \\ d_0 &= 0, d_1 = \frac{\mp 3Ea^2\mu B}{2A\sqrt{Ea^2\lambda P + BL}}, d_2 = 0, c = \pm a\sqrt{Ea^2\lambda P + BL}. \end{aligned}$$

set (2).

$$\begin{aligned} a_0 &= \frac{Ea^2\lambda}{A}, a_1 = \frac{3Ea^2\mu}{2A}, a_2 = 0, b_0 = \frac{\pm E^2a^4\lambda^2}{A\sqrt{-Ea^2\lambda P + BL}}, b_1 = \frac{\pm 3E^2a^4\lambda\mu}{2A\sqrt{-Ea^2\lambda P + BL}}, \\ b_2 &= 0, d_0 = \frac{\mp BEa^2\lambda}{A\sqrt{-Ea^2\lambda P + BL}}, d_1 = \frac{\mp 3Ea^2\mu B}{2A\sqrt{-Ea^2\lambda P + BL}}, d_2 = 0, \\ c &= \pm a\sqrt{-Ea^2\lambda P + BL}. \end{aligned}$$

Using Eq. (17), the solutions of Eq. (5) and set (1) we get

Case 1. where $\lambda > 0$ and $\mu \neq 0$,

$$\begin{aligned} u_{1,2} &= \frac{-3Ea^2\lambda}{2A} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} \left(ax \mp a\sqrt{Ea^2\lambda P + BL}t + k \right) \right), \\ v_{1,2} &= \frac{\pm 3E^2a^4\lambda^2}{2A\sqrt{Ea^2\lambda P + BL}} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} \left(ax \mp a\sqrt{Ea^2\lambda P + BL}t + k \right) \right), \\ w_{1,2} &= \frac{\pm 3Ea^2\lambda B}{2A\sqrt{Ea^2\lambda P + BL}} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} \left(ax \mp a\sqrt{Ea^2\lambda P + BL}t + k \right) \right). \\ u_{3,4} &= \frac{3Ea^2\lambda}{2A} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} \left(ax \pm a\sqrt{Ea^2\lambda P + BL}t + k \right) \right), \\ v_{3,4} &= \frac{\pm 3E^2a^4\lambda^2}{2A\sqrt{Ea^2\lambda P + BL}} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} \left(ax \pm a\sqrt{Ea^2\lambda P + BL}t + k \right) \right), \end{aligned}$$

$$w_{3,4} = \frac{\pm 3Ea^2\lambda B}{2A\sqrt{Ea^2\lambda P + BL}} \operatorname{csch}^2\left(\frac{\sqrt{\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right).$$

Case 2. where $\lambda < 0$ and $\mu \neq 0$,

$$u_{5,6} = \frac{-3Ea^2\lambda}{2A} \sec^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right),$$

$$v_{5,6} = \frac{\mp 3E^2a^4\lambda^2}{2A\sqrt{Ea^2\lambda P + BL}} \sec^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right),$$

$$w_{5,6} = \frac{\mp 3Ea^2\lambda B}{2A\sqrt{Ea^2\lambda P + BL}} \sec^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right).$$

$$u_{7,8} = \frac{-3Ea^2\lambda}{2A} \csc^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right),$$

$$v_{7,8} = \frac{\mp 3E^2a^4\lambda^2}{2A\sqrt{Ea^2\lambda P + BL}} \csc^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right),$$

$$w_{7,8} = \frac{\mp 3Ea^2\lambda B}{2A\sqrt{Ea^2\lambda P + BL}} \csc^2\left(\frac{\sqrt{-\lambda}}{2}\left(ax \pm a\sqrt{Ea^2\lambda P + BLt} + k\right)\right).$$

Case 3. where $\lambda = 0$ and $\mu \neq 0$,

$$u_{9,10} = \frac{6Ea^2}{A\left(ax \pm a\sqrt{BLt} + k\right)^2},$$

$$w_{9,10} = \frac{6Ea^2B}{A\sqrt{BL}\left(ax \pm a\sqrt{BLt} + k\right)^2},$$

where v is constant.

Case 4. where $\lambda = \theta^2$ and $\mu \neq 0$,

$$u_{11,12} = \frac{3Ea^2\theta^2 \left(\left(\frac{1+\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))}{1-\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))} \right)^2 - 1 \right)}{2A},$$

$$v_{11,12} = \frac{\pm 3Ea^4\theta^4 \left(\left(\frac{1+\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))}{1-\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))} \right)^2 - 1 \right)}{2A\sqrt{Ea^2\theta^2P+BL}},$$

$$w_{11,12} = \frac{\pm 3BEa^2\theta^2 \left(\left(\frac{1+\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))}{1-\exp(\theta(ax \pm a\sqrt{Ea^2\theta^2P+BLt+k}))} \right)^2 - 1 \right)}{2A\sqrt{Ea^2\theta^2P+BL}}.$$

Case 5. when $\lambda \neq 0$ and $\mu = 0$ are constants.

Using Eq. (17), the solutions of Eq. (5) and set (2) we get

Case 1. where $\lambda > 0$ and $\mu \neq 0$,

$$u_{13,14} = \frac{Ea^2\lambda}{A} \left(1 - \frac{3}{2} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-Ea^2\lambda P + BLt} + k) \right) \right),$$

$$v_{13,14} = \frac{\mp E^2a^4\lambda^2}{A\sqrt{-Ea^2\lambda P + BL}} \left(1 - \frac{3}{2} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-Ea^2\lambda P + BLt} + k) \right) \right),$$

$$w_{13,14} = \frac{\pm BEa^2\lambda}{A\sqrt{-Ea^2\lambda P + BL}} \left(1 - \frac{3}{2} \operatorname{sech}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-Ea^2\lambda P + BLt} + k) \right) \right).$$

$$u_{15,16} = \frac{Ea^2\lambda}{A} \left(1 + \frac{3}{2} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-Ea^2\lambda P + BLt} + k) \right) \right),$$

$$v_{15,16} = \frac{\mp E^2 a^4 \lambda^2}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 + \frac{3}{2} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right),$$

$$w_{15,16} = \frac{\pm B E a^2 \lambda}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 + \frac{3}{2} \operatorname{csch}^2 \left(\frac{\sqrt{\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right).$$

Case 2. where $\lambda < 0$ and $\mu \neq 0$,

$$u_{17,18} = \frac{E a^2 \lambda}{A} \left(1 - \frac{3}{2} \sec^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right),$$

$$v_{17,18} = \frac{\mp E^2 a^4 \lambda^2}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 - \frac{3}{2} \sec^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right),$$

$$w_{17,18} = \frac{\pm E a^2 \lambda B}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 - \frac{3}{2} \sec^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right).$$

$$u_{19,20} = \frac{E a^2 \lambda}{A} \left(1 - \frac{3}{2} \csc^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right),$$

$$v_{19,20} = \frac{\mp E^2 a^4 \lambda^2}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 - \frac{3}{2} \csc^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right),$$

$$w_{19,20} = \frac{\pm E a^2 \lambda B}{A \sqrt{-E a^2 \lambda P + BL}} \left(1 - \frac{3}{2} \csc^2 \left(\frac{\sqrt{-\lambda}}{2} (ax \pm a\sqrt{-E a^2 \lambda P + BL} t + k) \right) \right).$$

Case 3. where $\lambda = 0$ and $\mu \neq 0$, we obtain the same solutions $u_{9,10}, v_{9,10}$ and $w_{9,10}$.

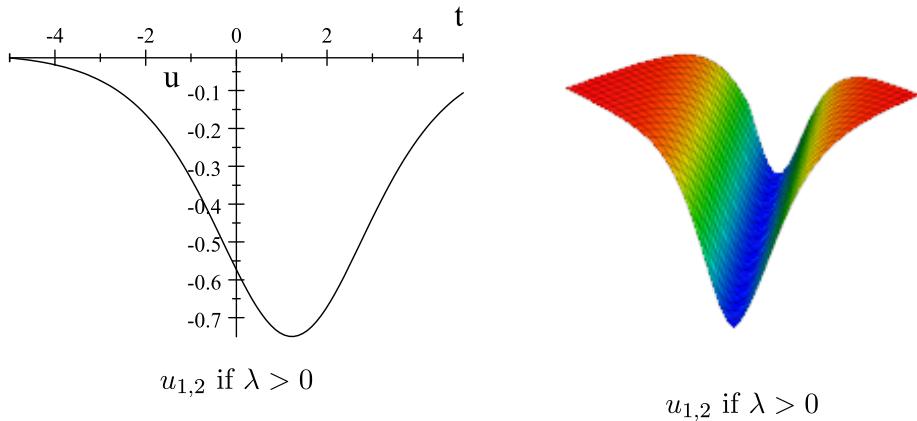
Case 4. where $\lambda = \theta^2$ and $\mu \neq 0$,

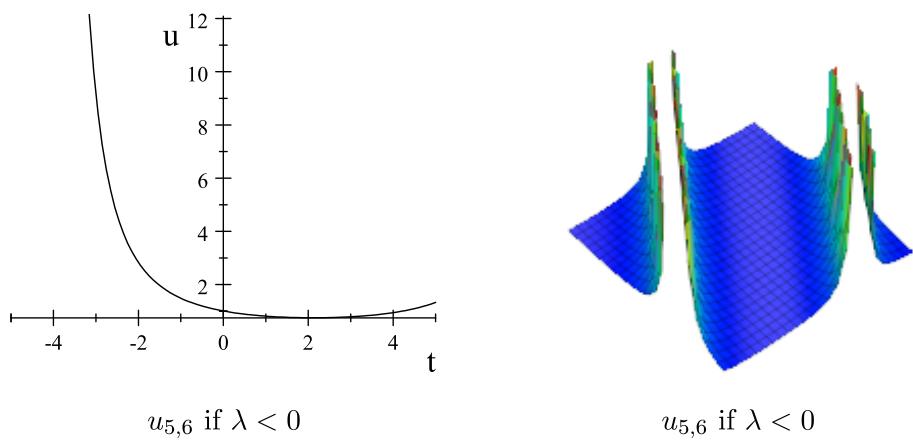
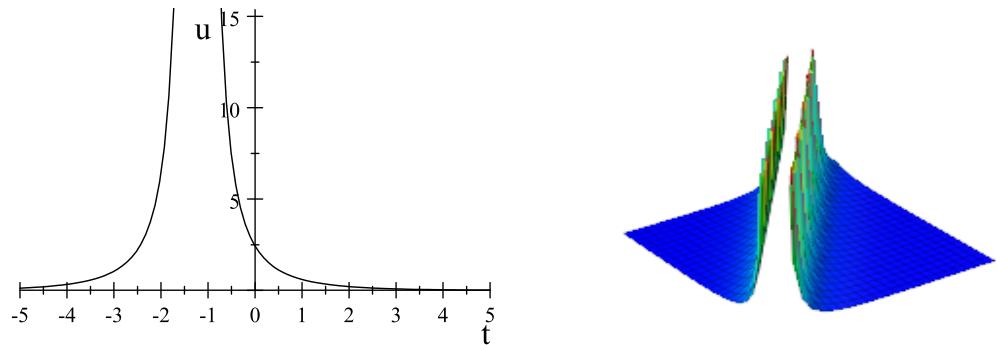
$$u_{21,22} = \frac{E a^2 \theta^2}{A} \left(\frac{-1 + 3 \left(\frac{1 + \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + BL} t + k))}{1 - \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + BL} t + k))} \right)^2}{2} \right),$$

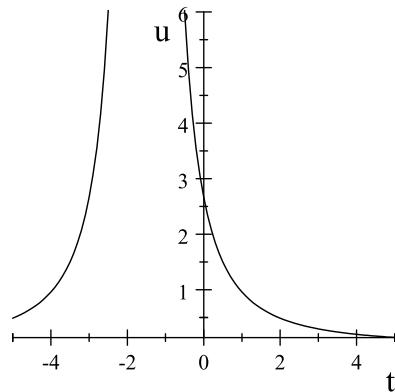
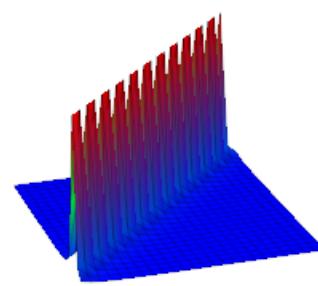
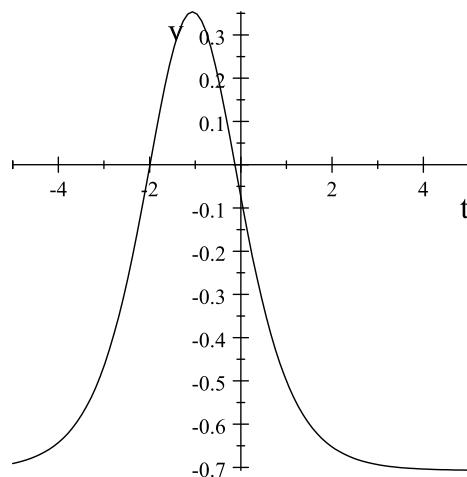
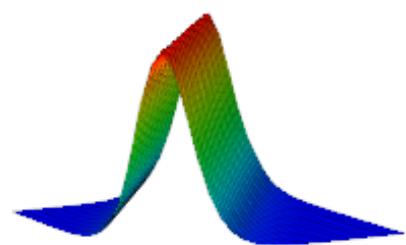
$$v_{21,22} = \frac{\mp E^2 a^4 \theta^4}{A \sqrt{-E a^2 \theta^2 P + B L}} \left(\frac{-1 + 3 \left(\frac{1 + \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + B L t} + k))}{1 - \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + B L t} + k))} \right)^2}{2} \right),$$

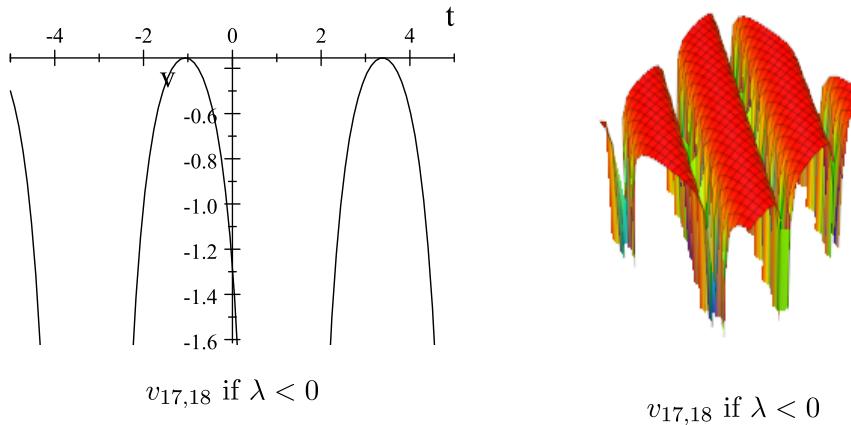
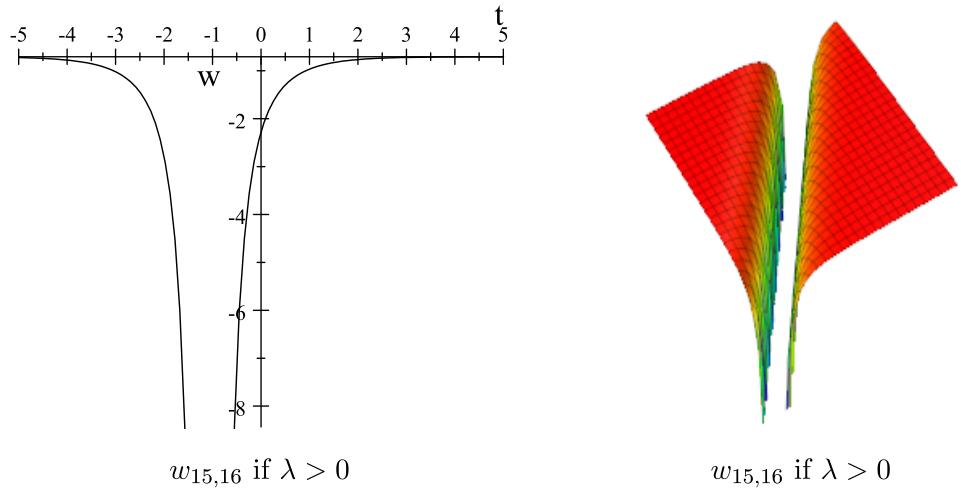
$$w_{21,22} = \frac{\pm B E a^2 \theta^2}{A \sqrt{-E a^2 \theta^2 P + B L}} \left(\frac{-1 + 3 \left(\frac{1 + \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + B L t} + k))}{1 - \exp(\theta(ax \pm a\sqrt{-E a^2 \theta^2 P + B L t} + k))} \right)^2}{2} \right).$$

Case 5. when $\lambda \neq 0$ and $\mu = 0$ are constants.





 $u_{9,10}$ if $\lambda = 0$  $u_{9,10}$ if $\lambda = 0$  $v_{13,14}$ if $\lambda > 0$  $v_{13,14}$ if $\lambda > 0$



4 Conclusion

In this paper, we presented a new method to solve a new extension system equations (esB). A new method has been successfully implemented to find new traveling wave solutions for some nonlinear partial differential equations. We expressed some of our new solutions graphically.

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